# On vertex Leibniz algebras 

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#### Abstract

In this paper, we study a notion of what we call vertex Leibniz algebra. This notion naturally extends that of vertex algebra without vacuum, which was previously introduced by Huang and Lepowsky. We show that every vertex algebra without vacuum can be naturally extended to a vertex algebra. On the other hand, we show that a vertex Leibniz algebra can be embedded into a vertex algebra if and only if it admits a faithful module. To each vertex Leibniz algebra we associate a vertex algebra without vacuum which is universal to the forgetful functor. Furthermore, from any Leibniz algebra $\mathfrak{g}$ we construct a vertex Leibniz algebra $V_{\mathfrak{g}}$ and show that $V_{\mathfrak{g}}$ can be embedded into a vertex algebra if and only if $\mathfrak{g}$ is a Lie algebra.


## 1 Introduction

The notion of vertex algebra has multi-faces. As one of many equivalent definitions, the notion of vertex algebra can be defined by using the existence of a vacuum and a stringy Jacobi identity as the main axioms, where a vacuum for a vertex algebra is analogous to an identity for a ring. This very Jacobi identity is also known to be equivalent to what were called weak commutativity (namely, locality) and weak associativity. This demonstrates a striking similarity between the notions of vertex algebra and commutative associative algebra with unit. On the other hand, a fundamental property for vertex algebras is what is called skew symmetry (see [FHL]), which is a stringy analog of the skew symmetry for a Lie algebra. This shows that vertex algebras are also analogous to Lie algebras.

In literature, besides the formal variable approach (see [FLM], [FHL]) to vertex algebras, there is also a $\mathcal{D}$-module approach (see [BD]). To bridge the $\mathcal{D}$-module approach and the formal variable approach, Huang and Lepowsky (see [HL]) introduced and studied a notion of what was called a vertex algebra without vacuum. The main axioms for a vertex algebra without vacuum in this sense are the Jacobi identity and skew symmetry (and one property involving the translation operator).

[^0]It is clear that the notion of vertex algebra without vacuum is a closer analog of the notion of Lie algebra (than that of vertex algebra).

In this paper, we study a notion of what we call vertex Leibniz algebra, which naturally generalizes the notion of vertex algebra without vacuum of Huang and Lepowsky. As it was mentioned before, one equivalent definition of a vertex algebra is to use the existence of a vacuum and the Jacobi identity as the main axioms. The notion of vertex Leibniz algebra is defined by simply dropping the existence of a vacuum from this definition, to leave Jacobi identity only as the main axiom. This notion generalizes that of vertex algebra without vacuum in the same way that the notion of Leibniz algebra generalizes that of Lie algebra.

One of the main motivations for studying vertex Leibniz algebras came from a previous work [LTW], in which a theory of what we called toroidal vertex algebras was developed. Toroidal vertex algebras are high dimension analogues of vertex algebras to a certain extent. For a toroidal vertex algebra, we have a Jacobi identity as the main axiom, but we do not have a vacuum with the usual creation property, neither do we have a skew symmetry. Another motivation came from certain studies ([Lo], [LP], [KW]; cf. [Ch], [Ca], [U]), in which Leibniz algebras were found to have important applications.

In this paper, we present various axiomatic results, to lay the foundation for further studies. We first revisit Huang and Lepowsky's notion of vertex algebra without vacuum. As an analog of a canonical exercise in classical ring theory, we show that every vertex algebra without vacuum can be embedded into a vertex algebra and every vertex algebra without vacuum admits a faithful representation. (Presumably, this was known to Huang and Lepowsky.) This shows that vertex algebras without vacuum are not much different from vertex algebras (with vacuum). On the other hand, vertex Leibniz algebras are quite different. From the definition, any closed subspace of a vertex algebra in the obvious sense is automatically a vertex Leibniz algebra, but not every vertex Leibniz algebra can be embedded into a vertex algebra. It is proved that a vertex Leibniz algebra $V$ can be embedded into a vertex algebra if and only if $V$ admits a faithful representation. This particularly implies that if the vertex operator map $Y(\cdot, x)$ of a vertex Leibniz algebra $V$ is injective, then $V$ is isomorphic to a vertex Leibniz subalgebra of a vertex algebra. In this paper, to each vertex Leibniz algebra we construct a vertex algebra without vacuum, which is universal to the obvious forgetful functor. Philosophically speaking, vertex Leibniz algebras are extensions of vertex algebras, whereas vertex algebras without vacuum are "subalgebras" of vertex algebras.

Also among the results of this paper, we establish an existence theorem of a vertex Leibniz algebra structure on a vector space with certain partial structures, which can be considered as an analog of a theorem of Xu (see [X1], [X2]). As an application we construct a vertex Leibniz algebra from any classical Leibniz algebra. More specifically, let $\mathfrak{g}$ be a Leibniz algebra. The tensor product $L(\mathfrak{g})=\mathfrak{g} \otimes \mathbb{C}\left[t, t^{-1}\right]$ (with $\mathbb{C}\left[t, t^{-1}\right]$ viewed as a commutative associative algebra) is a Leibniz algebra. Extend the left action of $\mathfrak{g}$ on $\mathfrak{g}$ to obtain a $\mathfrak{g} \otimes \mathbb{C}[t]$-module by letting $\mathfrak{g} \otimes t \mathbb{C}[t]$ act
trivially. Denote by $V_{\mathfrak{g}}$ the $L(\mathfrak{g})$-module induced from the $\mathfrak{g} \otimes \mathbb{C}[t]$-module $\mathfrak{g}$. It is proved that there exists a canonical vertex Leibniz algebra structure on $V_{\mathfrak{g}}$, which contains $\mathfrak{g}$ as a generating subspace. Furthermore, it is shown that if $\mathfrak{g}$ is not a Lie algebra, $V_{\mathfrak{g}}$ is an authentic vertex Leibniz algebra; it cannot be embedded into a vertex algebra.

This paper is organized as follows: In Section 2, we first recall or introduce the basic concepts of vertex algebra, vertex algebra without vacuum, and vertex Leibniz algebra, and then we give natural connections among them. In Section 3, we establish an analog of a theorem of Xu and then use this to associate vertex Leibniz algebras and their modules to loop Leibniz algebras.

Note added: After this paper had been completed, one of us (H.L) received a recent preprint [R2] of Thomas Robinson, and meanwhile Robinson's earlier paper [R1] was also brought to our attention. Among other results, Robinson had studied in [R1] a notion of vacuum free vertex algebra, where a vacuum free vertex algebra is a vertex Leibniz algebra in the sense of this present paper such that the vertex operator map is injective, and showed (Remark 4.1 therein) that any vacuum free vertex algebra can be embedded into a vertex algebra. There is a certain amount of overlap between [R2] and the present paper. More specifically, an ertex algebra in the sense of $[\mathrm{R} 2]$ is the same as a vertex Leibniz algebra, while a $D$ ertex algebra therein amounts to a vertex algebra without vacuum in the sense of Huang-Lepowsky. Furthermore, Lemma 2.7 and Theorem 2.8, and certain results analogous to Propositions 2.29 and 2.35 of this present paper have also been obtained in [R2]. We thank James Lepowsky for the information and thank Robinson for kindly sharing his preprint [R2] with us.

## 2 Vertex algebras, vertex algebras without vacuum, and vertex Leibniz algebras

In this section, we first recall the notion of vertex algebra and the basic properties, and we then recall the notion of vertex algebra without vacuum from [HL] and formulate a notion of vertex Leibniz algebra. As the main results, we establish canonical connections among these notions. For this paper, all vector spaces are assumed to be over $\mathbb{C}$ (the field of complex numbers), and $\mathbb{N}$ denotes the set of nonnegative integers.

We start with the notion of vertex algebra. The following is one of many equivalent definitions ([Bo], [FLM]; cf. [LL]):

Definition 2.1. A vertex algebra is a vector space $V$ equipped with a linear map

$$
\begin{align*}
Y(\cdot, x): & V \rightarrow \operatorname{Hom}(V, V((x))) \subset(\operatorname{End} V)\left[\left[x, x^{-1}\right]\right], \\
& v \mapsto Y(v, x)=\sum_{n \in \mathbb{Z}} v_{n} x^{-n-1} \quad\left(\text { where } v_{n} \in \operatorname{End} V\right) \tag{2.1}
\end{align*}
$$

and equipped with a distinguished vector $\mathbf{1} \in V$, called the vacuum vector, such that all the following conditions are satisfied for $u, v \in V$ :

$$
\begin{gather*}
Y(\mathbf{1}, x) v=v \quad \text { (the vacuum property), } \\
Y(v, x) \mathbf{1} \in V[[x]] \text { and } \lim _{x \rightarrow 0} Y(v, x) \mathbf{1}=v \text { (the creation property), } \\
x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right) Y\left(u, x_{1}\right) Y\left(v, x_{2}\right)-x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right) Y\left(v, x_{2}\right) Y\left(u, x_{1}\right) \\
=x_{2}^{-1} \delta\left(\frac{x_{1}-x_{0}}{x_{2}}\right) Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) \tag{2.2}
\end{gather*}
$$

(the Jacobi identity). The linear map $Y(\cdot, x)$ is called the vertex operator map, while for $v \in V, Y(v, x)$ is called the vertex operator associated to $v$.

Let $V$ be a vertex algebra. A (resp. faithful) $V$-module is a vector space $W$ equipped with a (resp. injective) linear map

$$
Y_{W}(\cdot, x): V \rightarrow \operatorname{Hom}(W, W((x))) \subset(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]
$$

such that $Y_{W}(\mathbf{1}, x)=1_{W}$ (the identity operator on $W$ ) and such that the Jacobi identity holds.

Note that for a vertex algebra $V$, due to the creation property the vertex operator map $Y(\cdot, x)$ is always injective. That is, the adjoint module (or representation) is always faithful.

Remark 2.2. It was proved in [LL] that the vacuum property (which is an analog of the left identity property for rings) in the definition of the notion of vertex algebra follows from the other axioms. This is not the case for the creation property (which is an analog of the right identity property for rings), though the creation property can be replaced with the condition that the vertex operator map is injective.

Let $V$ be a vertex algebra. Define a linear operator $\mathcal{D}$ on $V$ by

$$
\begin{equation*}
\mathcal{D}(v)=v_{-2} \mathbf{1}=\left.\frac{d}{d x}(Y(v, x) \mathbf{1})\right|_{x=0} \tag{2.3}
\end{equation*}
$$

for $v \in V$. Then

$$
\begin{align*}
& {[\mathcal{D}, Y(v, x)]=\frac{d}{d x} Y(v, x) \quad \text { (the } \mathcal{D} \text {-bracket-derivative property), }}  \tag{2.4}\\
& Y(\mathcal{D} v, x)=\frac{d}{d x} Y(v, x) \quad \text { for } v \in V \tag{2.5}
\end{align*}
$$

(the $\mathcal{D}$-derivative property), and

$$
\begin{equation*}
Y(u, x) v=e^{x \mathcal{D}} Y(v,-x) u \quad \text { for } u, v \in V \tag{2.6}
\end{equation*}
$$

(the skew symmetry).
The following is a very useful alternative definition of a vertex algebra (see [FHL], [DL], [Li1]; cf. [LL]):

Theorem 2.3. A vertex algebra can be equivalently defined as a vector space $V$ equipped with a linear map $Y(\cdot, x)$ as in (2.1), a vector $\mathbf{1} \in V$, satisfying the vacuum property and creation property, and equipped with a linear operator $D$ on $V$, satisfying $D \mathbf{1}=0$, the $D$-bracket-derivative property and the locality: For any $u, v \in V$, there exists a nonnegative integer $k$ such that

$$
\begin{equation*}
\left(x_{1}-x_{2}\right)^{k}\left[Y\left(u, x_{1}\right), Y\left(v, x_{2}\right)\right]=0 \tag{2.7}
\end{equation*}
$$

The following notion is due to Huang and Lepowsky (see [HL]):
Definition 2.4. A vertex algebra without vacuum ${ }^{4}$ is a vector space $V$ equipped with a linear map $Y(\cdot, x)$ as in (2.1) and a linear operator $D$ on $V$ such that the Jacobi identity, the $D$-derivative property (2.5), and skew symmetry (2.6) hold.

Remark 2.5. It was known (see [FHL]) that in the presence of skew symmetry, locality, namely weak commutativity, is equivalent to weak associativity. Therefore, in the definition of a vertex algebra without vacuum, the Jacobi identity can be equivalently replaced by either locality or weak associativity.

Remark 2.6. Let $A$ be a commutative associative algebra (possibly without a unit) with a derivation $D$. For $a \in A$, define $Y(a, x) \in\left(\operatorname{End}_{\mathbb{C}} A\right)[[x]]$ by $Y(a, x) b=\left(e^{x D} a\right) b$ for $b \in A$. Then $(A, Y, D)$ carries the structure of a vertex algebra without vacuum (see $[\mathrm{Bo}]$ ). On the other hand, assume that $(V, Y, D)$ is a vertex algebra without vacuum such that $Y(u, x) v \in V[[x]]$ for $u, v \in V$. Then one can show that $V$ is a commutative associative algebra with $D$ as a derivation, where $u \cdot v=\left.Y(u, x) v\right|_{x=0}$ for $u, v \in V$. Furthermore, we have $Y(u, x) v=\left(e^{x D} u\right) \cdot v$ for $u, v \in V$.

Lemma 2.7. Let $V$ be a vector space equipped with a linear map $Y(\cdot, x)$ as in (2.1) and let $D$ be a linear operator on $V$ such that skew symmetry holds. Then the $D$-bracket-derivative property is equivalent to the $D$-derivative property.

Proof. For $u, v \in V$, using skew symmetry one gets

$$
\begin{aligned}
& Y(D u, x) v-\frac{d}{d x} Y(u, x) v \\
= & e^{x D} Y(v,-x) D u-e^{x D} D Y(v,-x) u-e^{x D} \frac{d}{d x} Y(v,-x) u \\
= & e^{x D}\left(-[D, Y(v,-x)]+\frac{d}{d(-x)} Y(v,-x)\right) u .
\end{aligned}
$$

Then the equivalence follows immediately.

[^1]Define a notion of homomorphism of vertex algebras without vacuum in the obvious way: A homomorphism of vertex algebras without vacuum from $U$ to $V$ is a linear map $\psi: U \rightarrow V$, satisfying the condition that

$$
\begin{equation*}
\psi(D u)=D \psi(u) \quad \text { and } \quad \psi\left(Y(u, x) u^{\prime}\right)=Y(\psi(u), x) \psi\left(u^{\prime}\right) \tag{2.8}
\end{equation*}
$$

for $u, u^{\prime} \in U$.
We have the following analog of a well known classical result in ring theory:
Theorem 2.8. Let $(V, Y, D)$ be a vertex algebra without vacuum. Set $\bar{V}=V \oplus \mathbb{C} 1$, where $\mathbb{C} \mathbf{1}$ is a one-dimensional vector space with a distinguished base vector 1. Define a linear map

$$
\bar{Y}(\cdot, x): \bar{V} \rightarrow(\operatorname{End} \bar{V})\left[\left[x, x^{-1}\right]\right]
$$

by $\bar{Y}(\mathbf{1}, x)=1$ and

$$
\bar{Y}(u, x)(v+\lambda \mathbf{1})=Y(u, x) v+\lambda e^{x D} u
$$

for $u, v \in V, \lambda \in \mathbb{C}$. Then $(\bar{V}, \bar{Y}, \mathbf{1})$ carries the structure of a vertex algebra with $V$ as a vertex subalgebra without vacuum.
Proof. It is clear that $\bar{Y}(\cdot, x)$ maps $\bar{V}$ to $\operatorname{Hom}(\bar{V}, \bar{V}((x)))$. Extend $D$ to a linear operator $\bar{D}$ on $\bar{V}$ by defining $\bar{D}(\mathbf{1})=0$. For $u \in V, \alpha \in \mathbb{C}$, by definition we have

$$
\bar{Y}(u+\alpha \mathbf{1}, x) \mathbf{1}=e^{x D} u+\alpha \mathbf{1}=e^{x \bar{D}}(u+\alpha \mathbf{1}) .
$$

We see that the vacuum property and the creation property hold.
For $u, v \in V, \alpha \in \mathbb{C}$, using the $D$-bracket-derivative property (recall Lemma 2.7) we get

$$
\begin{aligned}
\bar{D} \cdot \bar{Y}(u, x)(v+\alpha \mathbf{1}) & =D\left(Y(u, x) v+\alpha e^{x D} u\right) \\
& =Y(u, x) D v+\frac{d}{d x} Y(u, x) v+\alpha D e^{x D} u \\
& =\bar{Y}(u, x) \bar{D}(v+\alpha \mathbf{1})+\frac{d}{d x} \bar{Y}(u, x)(v+\alpha \mathbf{1})
\end{aligned}
$$

This proves

$$
[\bar{D}, \bar{Y}(u, x)]=\frac{d}{d x} \bar{Y}(u, x) \quad \text { for } u \in V
$$

We also have $[\bar{D}, \bar{Y}(\mathbf{1}, x)]=\frac{d}{d x} \bar{Y}(\mathbf{1}, x)$.
Let $u, v, w \in V, \alpha \in \mathbb{C}$. By definition we have

$$
\begin{aligned}
\bar{Y}\left(u, x_{1}\right) \bar{Y}\left(v, x_{2}\right)(w+\alpha \mathbf{1}) & =\bar{Y}\left(u, x_{1}\right)\left(Y\left(v, x_{2}\right) w+\alpha e^{x_{2} D} v\right) \\
& =Y\left(u, x_{1}\right) Y\left(v, x_{2}\right) w+\alpha Y\left(u, x_{1}\right) e^{x_{2} D} v \\
\bar{Y}\left(v, x_{2}\right) \bar{Y}\left(u, x_{1}\right)(w+\alpha \mathbf{1})= & Y\left(v, x_{2}\right) Y\left(u, x_{1}\right) w+\alpha Y\left(v, x_{2}\right) e^{x_{1} D} u
\end{aligned}
$$

Furthermore, using the $D$-bracket-derivative property and skew symmetry we get

$$
\begin{aligned}
& Y\left(u, x_{1}\right) e^{x_{2} D} v=e^{x_{2} D} Y\left(u, x_{1}-x_{2}\right) v=e^{x_{1} D} Y\left(v,-x_{1}+x_{2}\right) u, \\
& Y\left(v, x_{2}\right) e^{x_{1} D} u=e^{x_{1} D} Y\left(v, x_{2}-x_{1}\right) u
\end{aligned}
$$

Let $k$ be a nonnegative integer such that

$$
\left(x_{1}-x_{2}\right)^{k}\left[Y\left(u, x_{1}\right), Y\left(v, x_{2}\right)\right]=0 \quad \text { and } \quad x^{k} Y(v, x) u \in V[[x]],
$$

so that

$$
\left(x_{1}-x_{2}\right)^{k} Y\left(v, x_{2}-x_{1}\right) u=\left(x_{1}-x_{2}\right)^{k} Y\left(v,-x_{1}+x_{2}\right) u .
$$

Then we obtain

$$
\left(x_{1}-x_{2}\right)^{k} \bar{Y}\left(u, x_{1}\right) \bar{Y}\left(v, x_{2}\right)=\left(x_{1}-x_{2}\right)^{k} \bar{Y}\left(v, x_{2}\right) \bar{Y}\left(u, x_{1}\right) .
$$

By Theorem 2.3, $(\bar{V}, \bar{Y}, \mathbf{1})$ carries the structure of a vertex algebra. It can be readily seen that $V$ is a vertex subalgebra without vacuum of $\bar{V}$.

Definition 2.9. Let $(V, Y, D)$ be a vertex algebra without vacuum. A (resp. faithful) $V$-module is a vector space $W$ equipped with a (resp. injective) linear map

$$
Y_{W}(\cdot, x): V \rightarrow \operatorname{Hom}(W, W((x))) \subset(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]
$$

such that the Jacobi identity holds and such that

$$
\begin{equation*}
Y_{W}(D v, x)=\frac{d}{d x} Y_{W}(v, x) \quad \text { for } v \in V . \tag{2.9}
\end{equation*}
$$

As an immediate consequence of Theorem 2.8, we have:
Corollary 2.10. Every vertex algebra without vacuum admits a faithful module.
The following shows that for a vertex algebra without vacuum $V$, a $V$-module exactly amounts to a $\bar{V}$-module:

Proposition 2.11. Let $V$ be a vertex algebra without vacuum and let $\bar{V}=V \oplus \mathbb{C} 1$ be the vertex algebra constructed in Theorem 2.8. Let $\left(W, Y_{W}\right)$ be any $V$-module. Extend $Y_{W}(\cdot, x)$ to a linear map

$$
\bar{Y}_{W}(\cdot, x): \bar{V} \rightarrow(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]
$$

by defining $\bar{Y}_{W}(\mathbf{1}, x)=1_{W}$. Then $\left(W, \bar{Y}_{W}\right)$ is a $\bar{V}$-module.
Proof. We need to prove that the Jacobi identity for any pair $(u, v)$ in $V \cup\{\mathbf{1}\}$ holds. If $u, v \in V$, or $u=v=1$, it is clear. If $u=\mathbf{1}, v \in V$, it is also clear. Consider the case with $u \in V, v=\mathbf{1}$. Using (2.9) we have

$$
Y_{W}\left(Y\left(u, x_{0}\right) \mathbf{1}, x_{2}\right)=Y_{W}\left(e^{x_{0} D} u, x_{2}\right)=Y_{W}\left(u, x_{2}+x_{0}\right)
$$

Then the Jacobi identity for the pair $(u, \mathbf{1})$ follows from basic delta-function properties.

Next, we study an analog of the notion of Leibniz algebra.
Definition 2.12. A vertex Leibniz algebra is a vector space $V$ equipped with a linear map $Y(\cdot, x)$ as in (2.1) such that Jacobi identity (2.2) holds.

Remark 2.13. Let $A$ be an associative algebra (possibly without a unit) such that $a(b c)=b(a c)$ for $a, b, c \in A$. Such an algebra is called a Perm algebra in literature (see [Ch], [CL]). Let $D$ be a linear endomorphism of $A$ such that

$$
(D(a b)-D(a) b-a D(b)) c=0 \quad \text { for } a, b, c \in A
$$

For $a \in A$, define $Y(a, x) \in\left(\operatorname{End}_{\mathbb{C}} A\right)[[x]]$ by $Y(a, x) b=\left(e^{x D} a\right) b$ for $b \in A$. It is straightforward to show that $(A, Y)$ carries the structure of a vertex Leibniz algebra such that the $D$-derivative property (2.5) holds. On the other hand, assume that $(V, Y)$ is a vertex Leibniz algebra such that $Y(u, x) v \in V[[x]]$ for $u, v \in V$. Define $u \cdot v=\left.(Y(u, x) v)\right|_{x=0}$ for $u, v \in V$. It is straightforward to show that $(V, \cdot)$ is a Perm algebra. If we in addition assume that there exists a linear operator $D$ on $V$ such that the $D$-derivative property (2.5) holds, then $Y(u, x) v=\left(e^{x D} u\right) \cdot v$ for $u, v \in V$. Furthermore, for $u, v, w \in V$, as $Y\left(u, x_{1}\right) w \in V\left[\left[x_{1}\right]\right]$, applying $\operatorname{Res}_{x_{1}}$ to the Jacobi identity for the triple $(u, v, w)$ we get

$$
Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) w=Y\left(u, x_{0}+x_{2}\right) Y\left(v, x_{2}\right) w
$$

Extracting the coefficient of $x_{0}^{0} x_{2}$ from both sides we obtain

$$
(D(u \cdot v)-D(u) \cdot v-u \cdot D(v)) \cdot w=0 \quad \text { for } u, v, w \in V
$$

Remark 2.14. By definition, a vertex algebra (equipped with the canonical operator $\mathcal{D}$ ) is a vertex algebra without vacuum, and a vertex algebra without vacuum is a vertex Leibniz algebra. On the other hand, let $V$ be a vertex algebra and suppose that $K$ is a subspace which is closed in the sense that

$$
a_{n} b \in K \quad \text { for } a, b \in K, n \in \mathbb{Z}
$$

It is clear that $K$ is a vertex Leibniz algebra. Furthermore, if $K$ is also $\mathcal{D}$-stable (recall (2.3)), then $K$ equipped with $\mathcal{D}$ (viewed as an operator on $K$ ) is a vertex algebra without vacuum.

Definition 2.15. Let $V$ be a vertex Leibniz algebra. A (resp. faithful) $V$-module is a vector space $W$ equipped with a (resp. injective) linear map

$$
Y_{W}(\cdot, x): V \rightarrow \operatorname{Hom}(W, W((x))) \subset(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]
$$

such that the Jacobi identity holds.
The following is a straightforward analog of a classical fact in the theory of Leibniz algebras (cf. [Ca]):

Lemma 2.16. Let $V$ be a vertex Leibniz algebra and let $\left(W, Y_{W}\right)$ be a $V$-module with a $V$-module homomorphism $\psi: W \rightarrow V$. Define a linear map $Y^{W}(\cdot, x): W \rightarrow$ $(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]$ by

$$
Y^{W}(w, x) w^{\prime}=Y_{W}(\psi(w), x) w^{\prime} \quad \text { for } w, w^{\prime} \in W
$$

Then $\left(W, Y^{W}\right)$ carries the structure of a vertex Leibniz algebra and $\psi$ is a homomorphism of vertex Leibniz algebras.

Example 2.17. Let $\mathfrak{g}$ be a general Lie algebra equipped with a non-degenerate symmetric invariant bilinear form $\langle\cdot, \cdot\rangle$. Associated to $(\mathfrak{g},\langle\cdot, \cdot\rangle)$, one has an affine Lie algebra $\hat{\mathfrak{g}}=\mathfrak{g} \otimes \mathbb{C}\left[t, t^{-1}\right] \oplus \mathbb{C}$. For any complex number $\ell$, we have a vertex algebra $V_{\hat{\mathfrak{g}}}(\ell, 0)$ (cf. [FZ]), where

$$
V_{\hat{\mathfrak{g}}}(\ell, 0)=U(\hat{\mathfrak{g}}) \otimes_{U(\mathfrak{g} \otimes \mathbb{C}[t]+\mathbb{C} \mathbf{k})} \mathbb{C}_{\ell},
$$

a generalized Verma $\hat{\mathfrak{g}}$-module induced from a 1-dimensional $(\mathfrak{g} \otimes \mathbb{C}[t]+\mathbb{C} \mathbf{k})$-module $\mathbb{C}_{\ell}=\mathbb{C}$ on which $\mathfrak{g} \otimes \mathbb{C}[t]$ acts trivially and $\mathbf{k}$ acts as scalar $\ell$. It is also known (cf. [Li1]) that every restricted $\hat{\mathfrak{g}}$-module $W$ of level $\ell$ is naturally a $V_{\hat{\mathfrak{g}}}(\ell, 0)$-module. Assume that $\mathfrak{g}$ is a finite-dimensional simple Lie algebra. Denote by $M_{\hat{\mathfrak{g}}}(\ell, 0)$ the Verma $\hat{\mathfrak{g}}$-module of level $\ell$ with highest weight 0 . Then $M_{\hat{\mathfrak{g}}}(\ell, 0)$ is a $V_{\hat{\mathfrak{g}}}(\ell, 0)$-module and the natural $\hat{\mathfrak{g}}$-module homomorphism from $M_{\hat{\mathfrak{g}}}(\ell, 0)$ to $V_{\hat{\mathfrak{g}}}(\ell, 0)$ is a $V_{\hat{\mathfrak{g}}}(\ell, 0)$-module homomorphism. By Lemma 2.16, $M_{\hat{\mathfrak{g}}}(\ell, 0)$ is naturally a vertex Leibniz algebra.

Remark 2.18. Note that in Lemma 2.16, for $w \in \operatorname{ker} \psi, w^{\prime} \in W$ we have $Y(w, x) w^{\prime}=$ 0 . Thus, if $\psi$ is not one-to-one, $W$ as a vertex Leibniz algebra cannot have a vacuum vector so that $W$ cannot be a vertex algebra even if $V$ is a vertex algebra.

Example 2.19. A special case of Lemma 2.16 gives an analog of the hemisemidirect product $\mathfrak{g} \ltimes_{H} W$ of a Lie algebra $\mathfrak{g}$ with a $\mathfrak{g}$-module $W$ (cf. [KW]). Let $V$ be a vertex algebra and let $W$ be a $V$-module. Then $W \oplus V$ is a $V$-module where the projection of $V \oplus W$ onto $V$ is a $V$-module homomorphism. In view of Lemma 2.16, $V+W$ becomes a vertex Leibniz algebra with

$$
\begin{equation*}
Y(u+w, x)\left(v+w^{\prime}\right)=Y(u, x) v+Y(u, x) w^{\prime} \quad \text { for } u, v \in V, w, w^{\prime} \in W \tag{2.10}
\end{equation*}
$$

From Remark 2.18, if $W \neq 0, V+W$ is not a vertex algebra. In fact, if $W \neq 0$, $V+W$ even cannot be embedded into a vertex algebra. This is because if $V+W$ is a vertex Leibniz subalgebra of a vertex algebra $K$, then

$$
w=Y(\mathbf{1}, x) w=e^{x \mathcal{D}} Y(w,-x) \mathbf{1}=0 \quad \text { for all } w \in W
$$

where $\mathbf{1}$ is the vacuum vector of $V$ and $\mathcal{D}$ is the $\mathcal{D}$-operator of $K$.

Example 2.20. Let $V$ be a vertex algebra and let $G$ be a finite automorphism group of $V$. Denote by $V^{G}$ the vertex subalgebra of $G$-fixed points in $V$ and define a linear map $\psi: V \rightarrow V^{G}$ by

$$
\psi(v)=\frac{1}{|G|} \sum_{g \in G} g v \quad \text { for } v \in V
$$

It can be readily seen that $\psi$ is a $V^{G}$-module homomorphism. In view of Lemma 2.16, $V$ becomes a vertex Leibniz algebra with the vertex operator map $Y_{G}(\cdot, x)$ : $V \rightarrow(\operatorname{End} V)\left[\left[x, x^{-1}\right]\right]$ given by

$$
\begin{equation*}
Y_{G}(u, x) v=\frac{1}{|G|} \sum_{g \in G} Y(g u, x) v \tag{2.11}
\end{equation*}
$$

for $u, v \in V$. We have

$$
Y_{G}(h u, x) v=Y_{G}(u, x) v, \quad Y_{G}(u, x)(h v)=h Y_{G}(u, x) v
$$

for $h \in G, u, v \in V$. On the other hand, by Lemma 2.16, $\psi$ is a vertex Leibniz algebra homomorphism. It is straightforward to show that ker $\psi$ is exactly the linear span of $g u-u$ for $g \in G, u \in V$. Consequently, $\psi$ gives rise to an isomorphism from the quotient vertex Leibniz algebra $V / \operatorname{ker} \psi$ to vertex algebra $V^{G}$.

We have the following conceptual result (see also [R1], Remark 4.1):
Proposition 2.21. Let $V$ be a vertex Leibniz algebra. Then $V$ admits a faithful module if and only if $V$ is a vertex Leibniz subalgebra of some vertex algebra. In particular, if the vertex operator map $Y(\cdot, x)$ of $V$ is injective, i.e., for any nonzero $u \in V$, there exists $v \in V$ such that $Y(u, x) v \neq 0$, then $V$ is a vertex Leibniz subalgebra of some vertex algebra.
Proof. Since the adjoint module for every vertex algebra is faithful, the "if" part is clear. Now, assume that $V$ has a faithful module $\left(W, Y_{W}\right)$. Set $U=\left\{Y_{W}(v, x) \mid v \in\right.$ $V\}$. It follows from the Jacobi identity that $U$ is a local subset of $\operatorname{Hom}(W, W((x)))$. From [Li1], $U$ generates a vertex algebra $\langle U\rangle$ inside $\operatorname{Hom}(W, W((x)))$, where the identity operator $1_{W}$ on $W$ serves as the vacuum vector and the vertex operator map, denoted by $Y_{\mathcal{E}}(\cdot, x)$, is given by

$$
\begin{aligned}
& Y_{\mathcal{E}}\left(\alpha(x), x_{0}\right) \beta(x) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x}{x_{0}}\right) \alpha\left(x_{1}\right) \beta(x)-x_{0}^{-1} \delta\left(\frac{x-x_{1}}{-x_{0}}\right) \beta(x) \alpha\left(x_{1}\right)\right)
\end{aligned}
$$

for $\alpha(x), \beta(x) \in\langle U\rangle$. For $u, v \in V$, taking $\alpha(x)=Y_{W}(u, x), \beta(x)=Y_{W}(v, x)$ we get

$$
\begin{aligned}
& Y_{\mathcal{E}}\left(Y_{W}(u, x), x_{0}\right) Y_{W}(v, x) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x}{x_{0}}\right) Y_{W}\left(u, x_{1}\right) Y_{W}(v, x)-x_{0}^{-1} \delta\left(\frac{x-x_{1}}{-x_{0}}\right) Y_{W}(v, x) Y_{W}\left(u, x_{1}\right)\right) \\
= & Y_{W}\left(Y\left(u, x_{0}\right) v, x\right) .
\end{aligned}
$$

This shows that the map $Y_{W}(\cdot, x)$ from $V$ to $\langle U\rangle$ is a homomorphism of vertex Leibniz algebras. As $Y_{W}(\cdot, x)$ is assumed to be injective, $V$ is isomorphic to a vertex Leibniz subalgebra of $\langle U\rangle$.

Let $V$ be a vertex Leibniz algebra. Recall that $I_{V}=\{v \in V \mid Y(v, x)=0\}$, which is an ideal of $V$. One sees that $V$ is a faithful module for the quotient vertex Leibniz algebra $V / I_{V}$. In view of Proposition 2.21, $V / I_{V}$ is isomorphic to a vertex Leibniz subalgebra of some vertex algebra. The following generalization is also immediate:

Corollary 2.22. Let $V$ be a vertex Leibniz algebra and let $\left(W, Y_{W}\right)$ be any $V$-module. Set

$$
I_{V}(W)=\left\{v \in V \mid Y_{W}(v, x)=0\right\}
$$

Then $I_{V}(W)$ is an ideal of $V$ and the quotient algebra $V / I_{V}(W)$ is isomorphic to a vertex Leibniz subalgebra of some vertex algebra.

Definition 2.23. Let $V$ be a vertex Leibniz algebra. Define

$$
\begin{equation*}
J_{V}=\cap_{W \in \mathcal{M}(V)} \operatorname{ker} Y_{W}(\cdot, x), \tag{2.12}
\end{equation*}
$$

an ideal of $V$, where $\mathcal{M}(V)$ denotes the collection of all $V$-modules.
Proposition 2.24. Let $V$ be a vertex Leibniz algebra. If $I$ is an ideal of $V$ such that $V / I$ is isomorphic to a vertex Leibniz subalgebra of some vertex algebra, then $I \supset J_{V}$. On the other hand, the quotient vertex Leibniz algebra $V / J_{V}$ is isomorphic to a vertex Leibniz subalgebra of some vertex algebra.

Proof. Assume that $V / I$ is a vertex Leibniz subalgebra of a vertex algebra $K$. Then $K$ is a faithful $V / I$-module, due to the creation property of $K$. This $V / I$-module structure on $K$ gives rise to a $V$-module structure $Y_{K}(\cdot, x)$ with ker $Y_{K}=I$. Thus $J_{V} \subset \operatorname{ker} Y_{K}=I$. For the second assertion, note that the direct sum of all $V$ modules is a faithful module for $V / J_{V}$. By Proposition 2.21, $V / J_{V}$ is isomorphic to a vertex Leibniz subalgebra of some vertex algebra.

As an immediate consequence we have:
Corollary 2.25. Let $V$ be a vertex Leibniz algebra. Then $V$ can be embedded into a vertex algebra if and only if $J_{V}=0$.

Next, we consider vertex algebras without vacuum.
Proposition 2.26. Let $V$ be a vertex Leibniz algebra and let $D$ be a linear operator on $V$ such that the $D$-derivative property holds. If $Y(\cdot, x)$ is injective, then $V$ is a vertex algebra without vacuum.

Proof. We need to show that skew symmetry holds. This basically follows from [FHL]. Let $u, v, w \in V$. Note that the left-hand side of the Jacobi identity has a symmetry

$$
\left(u, v, x_{1}, x_{2}, x_{0}\right) \leftrightarrow\left(v, u, x_{2}, x_{1},-x_{0}\right),
$$

from which one obtains

$$
\begin{equation*}
Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) w=Y\left(Y\left(v,-x_{0}\right) u, x_{2}+x_{0}\right) w . \tag{2.13}
\end{equation*}
$$

Using this and the $D$-derivative property we get

$$
\begin{equation*}
Y\left(Y\left(u, x_{0}\right) v, x_{2}\right)=Y\left(Y\left(v,-x_{0}\right) u, x_{2}+x_{0}\right)=Y\left(e^{x_{0} D} Y\left(v,-x_{0}\right) u, x_{2}\right) . \tag{2.14}
\end{equation*}
$$

Since $Y(\cdot, x)$ is injective, we immediately obtain skew symmetry.
Note that for a vertex algebra $V$, the operator $D$ is canonically defined by $D(v)=$ $v_{-2} 1$ for $v \in V$. Now, we discuss the uniqueness of operator $D$ for a vertex algebra without vacuum.

Let $V$ be a vertex Leibniz algebra. Set

$$
\begin{equation*}
I_{V}=\{v \in V \mid Y(v, x)=0\} . \tag{2.15}
\end{equation*}
$$

Then $I_{V}$ is an ideal of $V$ in the sense that $I_{V}$ is a subspace satisfying

$$
u_{n} v, \quad v_{n} u \in I_{V} \quad \text { for all } u \in V, v \in I_{V} .
$$

Let $\operatorname{Der}\left(V, I_{V}\right)$ denote the set of linear maps $\psi \in \operatorname{Hom}\left(V, I_{V}\right)$, satisfying

$$
\begin{equation*}
\psi(Y(u, x) v)=Y(\psi(u), x) v+Y(u, x) \psi(v) \quad \text { for } u, v \in V \tag{2.16}
\end{equation*}
$$

We have:
Proposition 2.27. Let $V$ be a vertex Leibniz algebra. Suppose that $D_{0}$ is a linear operator on $V$, satisfying (2.4) and (2.5). Then $D_{0}+\operatorname{Der}\left(V, I_{V}\right)$ is exactly the set of linear operators $D$ satisfying (2.4) and (2.5). In particular, if $V$ is a vertex algebra without vacuum such that $Y(\cdot, x)$ is injective, then the operator $D$ is unique.

Proof. Let $\psi \in \operatorname{Der}\left(V, I_{V}\right)$. For $u, v \in V$, since $Y(\psi(u), x)=0$ we have

$$
\psi(Y(u, x) v)=Y(\psi(u), x) v+Y(u, x) \psi(v)=Y(u, x) \psi(v) .
$$

Then

$$
\begin{aligned}
& {\left[D_{0}+\psi, Y(u, x)\right]=\left[D_{0}, Y(u, x)\right]=\frac{d}{d x} Y(u, x)} \\
& Y\left(\left(D_{0}+\psi\right) u, x\right)=Y\left(D_{0} u, x\right)=\frac{d}{d x} Y(u, x)
\end{aligned}
$$

On the other hand, suppose that $D$ is a linear operator on $V$, satisfying (2.4) and (2.5). Set $\psi=D-D_{0}$. For $u \in V$, we have

$$
Y(\psi(u), x)=Y(D u, x)-Y\left(D_{0} u, x\right)=\frac{d}{d x} Y(u, x)-\frac{d}{d x} Y(u, x)=0
$$

which implies $\psi(u) \in I_{V}$. Furthermore,

$$
[\psi, Y(u, x)]=[D, Y(u, x)]-\left[D_{0}, Y(u, x)\right]=\frac{d}{d x} Y(u, x)-\frac{d}{d x} Y(u, x)=0
$$

Thus $\psi \in \operatorname{Der}\left(V, I_{V}\right)$.
For convenience we formulate the following notion:
Definition 2.28. A vertex Leibniz algebra with $D$ is a vertex Leibniz algebra $V$ equipped with a linear operator $D$ on $V$ such that both the $D$-bracket-derivative property and the $D$-derivative property hold.

We have:
Proposition 2.29. Let $V$ be a vertex Leibniz algebra. Set

$$
\bar{V}=\mathbb{C}[D] \otimes V,
$$

where $D$ is a symbol. View $D$ as a linear operator on $\bar{V}$ in the obvious way and define a linear map

$$
\bar{Y}(\cdot, x): \bar{V} \rightarrow(\operatorname{End} \bar{V})\left[\left[x, x^{-1}\right]\right]
$$

by

$$
\begin{equation*}
\bar{Y}\left(e^{z D} u, x\right)\left(e^{z_{0} D} v\right)=e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v \tag{2.17}
\end{equation*}
$$

for $u, v \in V$. Then $(\bar{V}, \bar{Y}, D)$ carries the structure of a vertex Leibniz algebra with $D$. Furthermore, $\bar{V}$ contains $V$ as a vertex Leibniz subalgebra.

Proof. For $u, v \in V$, applying $\frac{\partial}{\partial z_{0}}$ to (2.17) we get

$$
\begin{aligned}
& \bar{Y}\left(e^{z D} u, x\right) D\left(e^{z_{0} D} v\right) \\
= & D e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v+e^{z_{0} D} \frac{\partial}{\partial z_{0}} Y\left(u, x+z-z_{0}\right) v \\
= & D e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v-\frac{\partial}{\partial x} e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v \\
= & D \bar{Y}\left(e^{z D} u, x\right)\left(e^{z_{0} D} v\right)-\frac{\partial}{\partial x} \bar{Y}\left(e^{z D} u, x\right)\left(e^{z_{0} D} v\right) .
\end{aligned}
$$

This gives

$$
\left[D, \bar{Y}\left(e^{z D} u, x\right)\right]=\frac{\partial}{\partial x} \bar{Y}\left(e^{z D} u, x\right)
$$

On the other hand, applying $\frac{\partial}{\partial z}$ to (2.17) we get

$$
\begin{aligned}
\bar{Y}\left(D e^{z D} u, x\right)\left(e^{z_{0} D} v\right) & =\frac{\partial}{\partial z} e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v \\
& =\frac{\partial}{\partial x} e^{z_{0} D} Y\left(u, x+z-z_{0}\right) v \\
& =\frac{\partial}{\partial x} \bar{Y}\left(e^{z D} u, x\right)\left(e^{z_{0} D} v\right)
\end{aligned}
$$

This proves $\bar{Y}(D a, x)=\frac{d}{d x} \bar{Y}(a, x)$ for $a \in \bar{V}$.
Let $u, v, w \in V$. By definition we have

$$
\begin{align*}
& \bar{Y}\left(e^{z_{1} D} u, x_{1}\right) \bar{Y}\left(e^{z_{2} D} v, x_{2}\right)\left(e^{z_{0} D} w\right) \\
= & \bar{Y}\left(e^{z_{1} D} u, x_{1}\right) e^{z_{0} D} Y\left(v, x_{2}+z_{2}-z_{0}\right) w \\
= & e^{z_{0} D} Y\left(u, x_{1}+z_{1}-z_{0}\right) Y\left(v, x_{2}+z_{2}-z_{0}\right) w \\
= & e^{z_{0} D} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right)} \frac{\partial}{\partial x_{2}} Y\left(u, x_{1}\right) Y\left(v, x_{2}\right) w . \tag{2.18}
\end{align*}
$$

Symmetrically, we have

$$
\begin{align*}
& \bar{Y}\left(e^{z_{2} D} v, x_{2}\right) \bar{Y}\left(e^{z_{1} D} u, x_{1}\right)\left(e^{z_{0} D} w\right) \\
& =e^{z_{0} D} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}} Y\left(v, x_{2}\right) Y\left(u, x_{1}\right) w . \tag{2.19}
\end{align*}
$$

On the other hand, we have

$$
\begin{align*}
& \bar{Y}\left(\bar{Y}\left(e^{z_{1} D} u, x_{0}\right)\left(e^{z_{2} D} v\right), x_{2}\right)\left(e^{z_{0} D} w\right) \\
= & \bar{Y}\left(e^{z_{2} D} Y\left(u, x_{0}+z_{1}-z_{2}\right) v, x_{2}\right)\left(e^{z_{0} D} w\right) \\
= & e^{z_{0} D} Y\left(Y\left(u, x_{0}+z_{1}-z_{2}\right) v, x_{2}+z_{2}-z_{0}\right) w \\
= & e^{z_{0} D} e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}} Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) w . \tag{2.20}
\end{align*}
$$

Note that if $A\left(x_{0}, x_{1}, x_{2}\right)$ is one of the following three delta functions

$$
x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right), x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right), x_{1}^{-1} \delta\left(\frac{x_{2}+x_{0}}{x_{1}}\right),
$$

we have

$$
\frac{\partial}{\partial x_{1}} A\left(x_{0}, x_{1}, x_{2}\right)=-\frac{\partial}{\partial x_{2}} A\left(x_{0}, x_{1}, x_{2}\right)=-\frac{\partial}{\partial x_{0}} A\left(x_{0}, x_{1}, x_{2}\right) .
$$

Consequently,

$$
e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}}} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}} A\left(x_{0}, x_{1}, x_{2}\right)=A\left(x_{0}, x_{1}, x_{2}\right)
$$

Notice that

$$
\begin{aligned}
& e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}}} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(u, x_{1}\right) Y\left(v, x_{2}\right) w\right) \\
= & e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(u, x_{1}\right) Y\left(v, x_{2}\right) w\right),
\end{aligned}
$$

$$
\begin{aligned}
& e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}}} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(v, x_{2}\right) Y\left(u, x_{1}\right) w\right) \\
= & e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(v, x_{2}\right) Y\left(u, x_{1}\right) w\right), \\
= & e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) w\right)} \\
\partial x_{0} & e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}\left(Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) w\right) .
\end{aligned}
$$

By definition, for the given vertex Leibniz algebra $(V, Y)$, we have the Jacobi identity for the ordered triple $(u, v, w)$. Applying $e^{\left(z_{1}-z_{2}\right) \frac{\partial}{\partial x_{0}}} e^{\left(z_{1}-z_{0}\right) \frac{\partial}{\partial x_{1}}} e^{\left(z_{2}-z_{0}\right) \frac{\partial}{\partial x_{2}}}$ to the both sides of the Jacobi identity for the ordered triple $(u, v, w)$, we obtain

$$
\begin{gathered}
x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right) \bar{Y}\left(e^{z_{1} D} u, x_{1}\right) \bar{Y}\left(e^{z_{2} D} v, x_{2}\right)\left(e^{z_{0} D} w\right) \\
\quad-x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right) \bar{Y}\left(e^{z_{2} D} v, x_{2}\right) \bar{Y}\left(e^{z_{1} D} u, x_{1}\right)\left(e^{z_{0} D} w\right) \\
= \\
x_{2}^{-1} \delta\left(\frac{x_{1}-x_{0}}{x_{2}}\right) \bar{Y}\left(\bar{Y}\left(e^{z_{1} D} u, x_{0}\right)\left(e^{z_{2} D} v\right), x_{2}\right)\left(e^{z_{0} D} w\right) .
\end{gathered}
$$

This implies the Jacobi identity that we need. This proves that $(\bar{V}, \bar{Y})$ carries the structure of a vertex Leibniz algebra. Combining the $D$-bracket-derivative property and the $D$-derivative property we see that $D$ is a derivation of $\bar{V}$.

It can be readily seen that the map $\bar{Y}$ extends the map $Y$, so the last assertion follows.

For a vertex Leibniz algebra $V$ with $D$, we define a $V$-module to be a module ( $W, Y_{W}$ ) for $V$ viewed as a vertex Leibniz algebra such that (2.9) holds.

The proof of Proposition 2.29 (with $z_{0}=0$ ) immediately gives:
Proposition 2.30. Let $V$ be a vertex Leibniz algebra and let $\left(W, Y_{W}\right)$ be a $V$-module. Define a linear map $\bar{Y}_{W}(\cdot, x): \bar{V} \rightarrow(\operatorname{End} W)\left[\left[x, x^{-1}\right]\right]$ by

$$
\bar{Y}_{W}\left(D^{n} v, x\right)=\left(\frac{d}{d x}\right)^{n} Y_{W}(v, x) \quad \text { for } n \in \mathbb{N}, v \in V
$$

Then $\left(W, \bar{Y}_{W}\right)$ carries the structure of a $\bar{V}$-module.
Next, we associate a vertex algebra without vacuum to each vertex Leibniz algebra with $D$.

Proposition 2.31. Let $V$ be a vertex Leibniz algebra with $D$. Let $J$ be the subspace of $V$, linearly spanned by vectors

$$
\begin{equation*}
u_{n} v-\sum_{i \geq 0}(-1)^{n+i-1} \frac{1}{i!} D^{i}\left(v_{n+i} u\right) \tag{2.21}
\end{equation*}
$$

for $u, v \in V, n \in \mathbb{Z}$. Then $J$ is a two-sided ideal and

$$
\begin{equation*}
Y(a, x) v=0 \quad \text { for } a \in J, v \in V . \tag{2.22}
\end{equation*}
$$

Furthermore, $V / J$ is a vertex algebra without vacuum.
Proof. Note that for $u, v \in V, n \in \mathbb{Z}$, we have

$$
\operatorname{Res}_{x} x^{n}\left(Y(u, x) v-e^{x D} Y(v,-x) u\right)=u_{n} v-\sum_{i \geq 0}(-1)^{n+i-1} \frac{1}{i!} D^{i}\left(v_{n+i} u\right) .
$$

Let $a, u, v \in V$. Using the $D$-bracket-derivative property and commutator formula, we get

$$
\begin{aligned}
& Y\left(a, x_{1}\right)\left(Y\left(u, x_{2}\right) v-e^{x_{2} D} Y\left(v,-x_{2}\right) u\right) \\
= & Y\left(a, x_{1}\right) Y\left(u, x_{2}\right) v-e^{x_{2} D} Y\left(a, x_{1}-x_{2}\right) Y\left(v,-x_{2}\right) u \\
= & Y\left(u, x_{2}\right) Y\left(a, x_{1}\right) v+\operatorname{Res}_{x_{0}} x_{1}^{-1} \delta\left(\frac{x_{2}+x_{0}}{x_{1}}\right) Y\left(Y\left(a, x_{0}\right) u, x_{2}\right) v \\
& -e^{x_{2} D} Y\left(a, x_{1}-x_{2}\right) Y\left(v,-x_{2}\right) u .
\end{aligned}
$$

Furthermore, from the Jacobi identity for the triple ( $a, v, u$ ) we get

$$
\begin{aligned}
& Y\left(a, x_{1}-x_{2}\right) Y\left(v,-x_{2}\right) u \\
= & Y\left(Y\left(a, x_{1}\right) v,-x_{2}\right)+\operatorname{Res}_{x_{0}} x_{1}^{-1} \delta\left(\frac{x_{2}+x_{0}}{x_{1}}\right) Y\left(v,-x_{2}\right) Y\left(a, x_{0}\right) u .
\end{aligned}
$$

Then we obtain

$$
\begin{aligned}
& Y\left(a, x_{1}\right)\left(Y\left(u, x_{2}\right) v-e^{x_{2} D} Y\left(v,-x_{2}\right) u\right) \\
= & Y\left(u, x_{2}\right) Y\left(a, x_{1}\right) v-e^{x_{2} D} Y\left(Y\left(a, x_{1}\right) v,-x_{2}\right) \\
& +\operatorname{Res}_{x_{0}} x_{2}^{-1} \delta\left(\frac{x_{1}-x_{0}}{x_{2}}\right)\left(Y\left(Y\left(a, x_{0}\right) u, x_{2}\right) v-e^{x_{2} D} Y\left(v,-x_{2}\right) Y\left(a, x_{0}\right) u\right) .
\end{aligned}
$$

It follows that $J$ is a left ideal of $V$. Furthermore, for $a \in J, v \in V$ we have

$$
Y(a, x) v=\left(Y(a, x) v-e^{x D} Y(v,-x) a\right)+e^{x D} Y(v,-x) a .
$$

From this it follows that $J$ is also a right ideal. On the other hand, by the $D$ derivative property and (2.13) we have

$$
\begin{aligned}
& Y\left(Y\left(u, x_{0}\right) v-e^{x_{0} D} Y\left(v,-x_{0}\right) u, x_{2}\right) a \\
= & Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) a-Y\left(Y\left(v,-x_{0}\right) u, x_{2}+x_{0}\right) a \\
= & 0 .
\end{aligned}
$$

This proves the first assertion. Then the quotient $V / J$ is a vertex Leibniz algebra equipped with a linear operator induced from $D$, satisfying the $D$-bracket-derivative property and the skew symmetry. Thus $V / J$ is a vertex algebra without vacuum.

Using the proof of Proposition 2.26 we immediately have:
Proposition 2.32. Let $V$ be a vertex Leibniz algebra with $D$. Then every $V$-module is naturally a V/J-module.

Let $V$ be a vertex Leibniz algebra. From Proposition 2.29, we have a vertex Leibniz algebra $\bar{V}=\mathbb{C}[D] \otimes V$ with $D$. Let $\bar{J}$ denote the (two-sided) ideal of $\bar{V}$, introduced in Proposition 2.31. Furthermore, by Proposition 2.31 the quotient algebra $\bar{V} / \bar{J}$ is a vertex algebra without vacuum.

Definition 2.33. Let $V$ be a vertex Leibniz algebra. We define $\widetilde{V}$ to be the vertex-algebra-without-vacuum $\bar{V} / \bar{J}$.

Remark 2.34. Let $V$ be a vertex Leibniz algebra. From Proposition 2.30, the category of $V$-modules is canonically isomorphic to the category of $\bar{V}$-modules. On the other hand, from Proposition 2.32 the category of $\bar{V}$-modules is canonically isomorphic to the category of $\widetilde{V}$-modules.

As $V$ is a vertex Leibniz subalgebra of $\bar{V}$ and $\widetilde{V}$ is a quotient algebra of $\bar{V}$, we have a canonical homomorphism of vertex Leibniz algebras

$$
\begin{equation*}
\pi_{V}: V \rightarrow \widetilde{V} \tag{2.23}
\end{equation*}
$$

Recall from Theorem 2.8 that $\widetilde{V}$ can be embedded into a vertex algebra. Then $\pi_{V}$ may be composed with this embedding to give a homomorphism from any vertex Leibniz algebra $V$ to a vertex algebra.

The following is a universal property of $\tilde{V}$ :
Proposition 2.35. Let $V$ be a vertex Leibniz algebra as before, let $K$ be any vertex algebra without vacuum and let $\psi: V \rightarrow K$ be any homomorphism of vertex Leibniz algebras. Then there exists a unique homomorphism $\tilde{\psi}$ of vertex algebras without vacuum from $\widetilde{V}$ to $K$ such that $\tilde{\psi} \circ \pi_{V}=\psi$.

Proof. It is clear that $\widetilde{V}$ as a vertex algebra without vacuum is generated by $\pi_{V}(V)$, so the uniqueness follows immediately. We now establish the existence. First, we define a linear map $\bar{\psi}: \bar{V} \rightarrow K$ by $\bar{\psi}\left(D^{n} v\right)=D^{n} \psi(v)$ for $n \in \mathbb{N}, v \in V$, where we abuse $D$ also for the $D$-operator of $K$. This is a homomorphism of vertex Leibniz algebras, commuting with $D$. Then $\bar{\psi}$ reduces to a homomorphism of vertex algebras without vacuum from $\widetilde{V}$ to $K$.

As an immediate consequence we have (cf. Proposition 2.21):
Corollary 2.36. Let $V$ be a vertex Leibniz algebra. Then homomorphism $\pi_{V}$ is injective if and only if $V$ is a vertex Leibniz subalgebra of some vertex algebra and if and only if $V$ admits a faithful representation.

We also have:

Proposition 2.37. Let $V$ be a vertex Leibniz algebra. Then $J_{V}=\operatorname{ker} \pi_{V}$.
Proof. Noticing that homomorphism $\pi_{V}$ from $V$ to $\widetilde{V}$ gives rise to a representation of $V$ on $\widetilde{V}$, from definition we have $J_{V} \subset \operatorname{ker} \pi_{V}$. On the other hand, from Proposition $2.24 V / J_{V}$ can be embedded into a vertex algebra $K$, so we have a homomorphism of vertex Leibniz algebras $f: V \rightarrow K$ with ker $f=J_{V}$. By Proposition 2.35, there exists a homomorphism of vertex algebras without vacuum $\psi: \widetilde{V} \rightarrow K$ such that $f=\psi \circ \pi_{V}$. Then ker $\pi_{V} \subset \operatorname{ker} f=J_{V}$. Therefore, $\operatorname{ker} \pi_{V}=J_{V}$.

We end this section with the following observation:
Corollary 2.38. Let $V$ be a vertex Leibniz algebra. A necessary condition that $V$ can be embedded into a vertex algebra is that for $u, v \in V, u_{m} v=(-1)^{m-1} v_{m} u$, where $m \in \mathbb{Z}$ such that $v_{m+j} u=0$ for all $j>0$.

Proof. This is because

$$
u_{m} v+(-1)^{m} v_{m} u=u_{m} v-(-1)^{m-1} v_{m} u-\sum_{j \geq 1}(-1)^{m+j-1} \frac{1}{j!} D^{j} v_{m+j} u
$$

which lies in ker $\pi_{V}\left(=J_{V}\right)$.

## 3 Construction of vertex Leibniz algebras

In this section, we first establish an analog of a theorem of Xiaoping Xu and then using this we associate a vertex Leibniz algebra $V_{\mathfrak{g}}$ to each Leibniz algebra $\mathfrak{g}$ and associate a $V_{\mathfrak{g}}$-module to every $\mathfrak{g}$-module.

The following is a vertex Leibniz algebra analog of a theorem of Xu (see [X2]; cf. [LL]):

Theorem 3.1. Let $V$ be a vector space equipped with a linear map

$$
\begin{aligned}
Y(\cdot, x): & V \rightarrow \operatorname{Hom}(V, V((x))) \subset(\operatorname{End} V)\left[\left[x, x^{-1}\right]\right], \\
& v \mapsto Y(v, x)=\sum_{n \in \mathbb{Z}} v_{n} x^{-n-1}
\end{aligned}
$$

and let $U$ be a subset of $V$. Assume that all the following conditions are satisfied: For $u, v \in U$, there exists a nonnegative integer $k$ such that

$$
\left(x_{1}-x_{2}\right)^{k} Y\left(u, x_{1}\right) Y\left(v, x_{2}\right)=\left(x_{1}-x_{2}\right)^{k} Y\left(v, x_{2}\right) Y\left(u, x_{1}\right)
$$

$V$ is linearly spanned by vectors

$$
u_{m_{1}}^{(1)} \cdots u_{m_{r}}^{(r)} u
$$

for $u^{(1)}, \ldots, u^{(r)}, u \in U, m_{1}, \ldots, m_{r} \in \mathbb{Z}$ with $r \in \mathbb{N}$; and for all $u \in U, v \in V$,

$$
\begin{align*}
& Y\left(Y\left(u, x_{0}\right) v, x_{2}\right) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right) Y\left(u, x_{1}\right) Y\left(v, x_{2}\right)-x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right) Y\left(v, x_{2}\right) Y\left(u, x_{1}\right)\right) . \tag{3.1}
\end{align*}
$$

Then $(V, Y)$ carries the structure of a vertex Leibniz algebra.
Proof. Set

$$
\tilde{U}=\{Y(u, x) \mid u \in U\} \subset \operatorname{Hom}(V, V((x))) .
$$

From assumption, $\tilde{U}$ is a local subset. Then by a result of [Li1], $\tilde{U}$ generates a vertex algebra $\langle\tilde{U}\rangle$, where $1_{V}$ serves as the vacuum vector and the vertex operator map, denoted by $Y_{\mathcal{E}}(\cdot, x)$, is given by

$$
\begin{align*}
& Y_{\mathcal{E}}\left(\alpha(x), x_{0}\right) \beta(x) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x}{x_{0}}\right) \alpha\left(x_{1}\right) \beta(x)-x_{0}^{-1} \delta\left(\frac{x-x_{1}}{-x_{0}}\right) \beta(x) \alpha\left(x_{1}\right)\right) \tag{3.2}
\end{align*}
$$

for $\alpha(x), \beta(x) \in \operatorname{Hom}(V, V((x)))$. It was also proved therein that $\langle\tilde{U}\rangle$ is also a local subspace. For $a \in U, v \in V$, by (3.1) and (3.2) we have

$$
\begin{align*}
& Y\left(Y\left(a, x_{0}\right) v, x\right) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x}{x_{0}}\right) Y\left(a, x_{1}\right) Y(v, x)-x_{0}^{-1} \delta\left(\frac{x-x_{1}}{-x_{0}}\right) Y(v, x) Y\left(a, x_{1}\right)\right) \\
= & Y_{\mathcal{E}}\left(Y(a, x), x_{0}\right) Y(v, x) . \tag{3.3}
\end{align*}
$$

It follows from this and the span assumption that $Y(\cdot, x)$ maps $V$ into $\langle\tilde{U}\rangle$. Since $\langle\tilde{U}\rangle$ is a local subspace of $\operatorname{Hom}(V, V((x))),\{Y(v, x) \mid v \in V\}$ as a subset of $\langle\tilde{U}\rangle$ is local. Recall that the Jacobi identity amounts to weak commutativity and weak associativity. Now it remains to establish weak associativity, which will be achieved in the following by induction.

Let $K$ consist of each $u \in V$ such that (3.1) holds for every $v \in V$. Now, let $a, b \in K, v \in V$. From (3.1) with $(a, b)$ in the places of $(u, v)$, there exists a nonnegative integer $l$ such that

$$
\left(x_{0}+y_{0}\right)^{l} Y\left(Y\left(a, x_{0}\right) b, y_{0}\right) v=\left(x_{0}+y_{0}\right)^{l} Y\left(a, x_{0}+y_{0}\right) Y\left(b, y_{0}\right) v .
$$

Using this, (3.3), and the weak associativity for $\langle\tilde{U}\rangle$, replacing $l$ with a large one if
necessary, we have

$$
\begin{aligned}
& \left(x_{0}+y_{0}\right)^{l} Y\left(Y\left(Y\left(a, x_{0}\right) b, y_{0}\right) v, z_{0}\right) \\
= & \left(x_{0}+y_{0}\right)^{l} Y\left(Y\left(a, x_{0}+y_{0}\right) Y\left(b, y_{0}\right) v, z_{0}\right) \\
= & \left(x_{0}+y_{0}\right)^{l} Y_{\mathcal{E}}\left(\overline{Y\left(a, z_{0}\right)}, x_{0}+y_{0}\right) \overline{Y\left(Y\left(b, y_{0}\right) v, z_{0}\right)} \\
= & \left(x_{0}+y_{0}\right)^{l} Y_{\mathcal{E}}\left(\overline{Y\left(a, z_{0}\right)}, x_{0}+y_{0}\right) Y_{\mathcal{E}}\left(\overline{Y\left(b, z_{0}\right)}, y_{0}\right) \overline{Y\left(v, z_{0}\right)} \\
= & \left(x_{0}+y_{0}\right)^{l} Y_{\mathcal{E}}\left(Y_{\mathcal{E}}\left(\overline{Y\left(a, z_{0}\right)}, x_{0}\right) \overline{Y\left(b, z_{0}\right)}, y_{0}\right) \overline{Y\left(v, z_{0}\right)} \\
= & \left(x_{0}+y_{0}\right)^{l} Y_{\mathcal{E}}\left(\overline{Y\left(Y\left(a, x_{0}\right) b, z_{0}\right)}, y_{0}\right) \overline{Y\left(v, z_{0}\right)},
\end{aligned}
$$

where $\bar{X}=X$ for all the bar objects; the only purpose is to make the equation easier to read. Multiplying both sides by formal series $\left(y_{0}+x_{0}\right)^{-l}$ we obtain

$$
Y\left(Y\left(Y\left(a, x_{0}\right) b, y_{0}\right) v, z_{0}\right)=Y_{\mathcal{E}}\left(\overline{Y\left(Y\left(a, x_{0}\right) b, z_{0}\right)}, y_{0}\right) \overline{Y\left(v, z_{0}\right)} .
$$

Furthermore, we have

$$
\begin{aligned}
& Y\left(Y\left(Y\left(a, x_{0}\right) b, y_{0}\right) v, z_{0}\right) \\
= & Y_{\mathcal{E}}\left(\overline{Y\left(Y\left(a, x_{0}\right) b, z_{0}\right)}, y_{0}\right) \overline{Y\left(v, z_{0}\right)} \\
= & \operatorname{Res}_{x_{1} y_{0}^{-1} \delta\left(\frac{x_{1}-z_{0}}{y_{0}}\right) Y\left(Y\left(a, x_{0}\right) b, x_{1}\right) Y\left(v, z_{0}\right)} \\
& -\operatorname{Res}_{x_{1} y_{0}^{-1} \delta\left(\frac{z_{0}-x_{1}}{-y_{0}}\right) Y\left(v, z_{0}\right) Y\left(Y\left(a, x_{0}\right) b, x_{1}\right) .} .
\end{aligned}
$$

This shows that $a_{m} b \in K$ for $m \in \mathbb{Z}$. It follows from induction and the span assumption that $V=K$. This proves that (3.1) holds for all $u, v \in V$. Then weak associativity follows. Therefore, $(V, Y)$ carries the structure of a vertex Leibniz algebra.

Remark 3.2. Recall that a (left) Leibniz algebra is a non-associative algebra $A$ satisfying the Leibniz role:

$$
a(b c)=(a b) c+b(a c) \quad \text { for } a, b, c \in A
$$

Let $J$ be the subspace linearly spanned by $a^{2}$ for $a \in A$. A simple fact is that $J \cdot A=0$ and $A \cdot J \subset J$, which implies that $J$ is a two-sided ideal of $A$. Furthermore, the quotient algebra $A / J$ is a Lie algebra.

Now, let $\mathfrak{g}$ be a Leibniz algebra. Form the Loop algebra $L(\mathfrak{g})=\mathfrak{g} \otimes \mathbb{C}\left[t, t^{-1}\right]$, where for $a, b \in \mathfrak{g}, m, n \in \mathbb{Z}$,

$$
\begin{equation*}
\left[a \otimes t^{m}, b \otimes t^{n}\right]=[a, b] \otimes t^{m+n} \tag{3.4}
\end{equation*}
$$

It can be readily seen that the loop algebra $L(\mathfrak{g})$ is also a Leibniz algebra.

Remark 3.3. Let $\mathfrak{g}$ be a Leibniz algebra and let $\langle\cdot, \cdot\rangle$ be a bilinear form on $\mathfrak{g}$. Consider the affinization $\hat{\mathfrak{g}}=\mathfrak{g}\left[t, t^{-1}\right] \oplus \mathbb{C} \mathbf{k}$, where

$$
\begin{aligned}
& {[\mathbf{k}, \hat{\mathfrak{g}}]=0=[\hat{\mathfrak{g}}, \mathbf{k}]} \\
& {\left[a \otimes t^{m}, b \otimes t^{n}\right]=[a, b] \otimes t^{m+n}+m\langle a, b\rangle \delta_{m+n, 0} \mathbf{k}}
\end{aligned}
$$

for $a, b \in \mathfrak{g}, m, n \in \mathbb{Z}$. It is straightforward to show that $\hat{\mathfrak{g}}$ is a Leibniz algebra if and only if

$$
\begin{equation*}
\langle a,[b, c]\rangle=\langle[a, b], c\rangle=-\langle b,[a, c]\rangle \quad \text { for } a, b, c \in \mathfrak{g} . \tag{3.5}
\end{equation*}
$$

From this, we see that if $\langle\cdot, \cdot\rangle$ is non-degenerate, then $\hat{\mathfrak{g}}$ is a Leibniz algebra if and only if $\mathfrak{g}$ is a Lie algebra and $\langle\cdot, \cdot\rangle$ is an invariant bilinear form.

Denote by $L(\mathfrak{g})_{\text {Lie }}$ the associated Lie algebra. Recall that vectors $[u, u]$ for $u \in$ $L(\mathfrak{g})$ linearly span a two-sided ideal of $L(\mathfrak{g})$ and $L(\mathfrak{g})_{\text {Lie }}$ is the quotient algebra.
Remark 3.4. Note that we have two Lie algebras $L(\mathfrak{g})_{\text {Lie }}$ and $L\left(\mathfrak{g}_{L i e}\right)$. We here show that the two Lie algebras are actually isomorphic. Let $J(\mathfrak{g})$ and $J(L(\mathfrak{g}))$ denote the ideals of $\mathfrak{g}$ and $L(\mathfrak{g})$, respectively. We need to show that $J(L(\mathfrak{g}))=J(\mathfrak{g}) \otimes \mathbb{C}\left[t, t^{-1}\right]$. For any $a, b \in \mathfrak{g}, m, n \in \mathbb{Z}$, we have

$$
\left[a \otimes t^{m}, b \otimes t^{n}\right]+\left[b \otimes t^{n}, a \otimes t^{m}\right]=([a, b]+[b, a]) \otimes t^{m+n} \in J(\mathfrak{g}) \otimes \mathbb{C}\left[t, t^{-1}\right] .
$$

It follows that $J(L(\mathfrak{g})) \subset J(\mathfrak{g}) \otimes \mathbb{C}\left[t, t^{-1}\right]$. On the other hand, for $a \in \mathfrak{g}, m \in \mathbb{Z}$, we have

$$
[a, a] \otimes t^{m}=\frac{1}{2}\left(\left[a \otimes t^{m}, a \otimes 1\right]+\left[a \otimes 1, a \otimes t^{m}\right]\right) \in J(L(\mathfrak{g})) .
$$

This implies $J(\mathfrak{g}) \otimes \mathbb{C}\left[t, t^{-1}\right] \subset J(L(\mathfrak{g}))$. Thus $J(L(\mathfrak{g}))=J(\mathfrak{g}) \otimes \mathbb{C}\left[t, t^{-1}\right]$.
A left $\mathfrak{g}$-module is a vector space $W$ on which $\mathfrak{g}$ acts from left such that

$$
\begin{equation*}
a(b w)-b(a w)=[a, b] w \quad \text { for } a, b \in \mathfrak{g}, w \in W \text {. } \tag{3.6}
\end{equation*}
$$

It can be readily seen that a left $\mathfrak{g}$-module exactly amounts to a module for the associated Lie algebra $\mathfrak{g}_{\text {Lie }}$. Note that a Leibniz algebra $\mathfrak{g}$ itself is always a left $\mathfrak{g}$-module.

Let $U$ be a (left) $\mathfrak{g}$-module, which amounts to a $\mathfrak{g}_{\text {Lie }}$-module. Let $\mathfrak{g}_{\text {Lie }} \otimes t \mathbb{C}[t]$ act trivially on $U$, to make $U$ an $L\left(\mathfrak{g}_{\text {Lie }}\right)^{+}$-module, where

$$
L\left(\mathfrak{g}_{L i e}\right)^{+}=\mathfrak{g}_{L i e} \otimes \mathbb{C}[t]=\mathfrak{g}_{L i e}+\left(\mathfrak{g}_{L i e} \otimes t \mathbb{C}[t]\right) .
$$

Form an induced module

$$
\begin{equation*}
V_{\mathfrak{g}}(U)=U\left(L\left(\mathfrak{g}_{L i e}\right)\right) \otimes_{U\left(L\left(\mathfrak{g}_{L i e}\right)^{+}\right)} U . \tag{3.7}
\end{equation*}
$$

It follows that $V_{\mathfrak{g}}(U)$ is a restricted $L(\mathfrak{g})$-module in the sense that for any $a \in \mathfrak{g}, w \in$ $V_{\mathfrak{g}}(U),\left(a \otimes t^{n}\right) w=0$ for $n$ sufficiently large. Set

$$
\begin{equation*}
V_{\mathfrak{g}}=V_{\mathfrak{g}}(\mathfrak{g})=U\left(L\left(\mathfrak{g}_{L i e}\right)\right) \otimes_{U\left(L\left(\mathfrak{g}_{L i e}\right)^{+}\right)} \mathfrak{g} . \tag{3.8}
\end{equation*}
$$

We have:

Theorem 3.5. There exists a vertex Leibniz algebra structure on $V_{\mathfrak{g}}$, which is uniquely determined by the condition that $Y(a, x)=a(x)$ for $a \in \mathfrak{g}$, where

$$
a(x)=\sum_{n \in \mathbb{Z}}\left(a \otimes t^{n}\right) x^{-n-1} .
$$

Furthermore, for any restricted $L(\mathfrak{g})$-module $W$, there is a $V_{\mathfrak{g}}$-module structure $Y_{W}(\cdot, x)$ on $W$, which is uniquely determined by the condition that

$$
Y_{W}(a, x)=a(x) \quad \text { for } a \in \mathfrak{g} .
$$

Proof. Let $W$ be any restricted $L(\mathfrak{g})$-module. Set

$$
U_{W}=\{a(x) \mid a \in \mathfrak{g}\} \subset \mathcal{E}(W)(=\operatorname{Hom}(W, W((x))))
$$

For any $a, b \in \mathfrak{g}$, from the commutation relation of $L(\mathfrak{g})$ we have

$$
\begin{equation*}
\left[a\left(x_{1}\right), b\left(x_{2}\right)\right]=[a, b]\left(x_{2}\right) x_{1}^{-1} \delta\left(\frac{x_{2}}{x_{1}}\right), \tag{3.9}
\end{equation*}
$$

which implies

$$
\left(x_{1}-x_{2}\right)\left[a\left(x_{1}\right), b\left(x_{2}\right)\right]=0 .
$$

Thus $U_{W}$ is a local subset of $\mathcal{E}(W)$. By a result of [Li1], $U_{W}$ generates a vertex algebra $\left\langle U_{W}\right\rangle$ where the vertex operator map is denoted by $Y_{\mathcal{E}}(\cdot, x)$ and the identity operator $1_{W}$ is the vacuum vector. Furthermore, $W$ is a faithful $\left\langle U_{W}\right\rangle$-module with $Y_{W}(u(x), z)=u(z)$ for $u(x) \in\left\langle U_{W}\right\rangle$. With (3.9), from [Li1] (Lemma 2.3.5) we have

$$
\begin{equation*}
\left[Y_{\mathcal{E}}\left(a(x), x_{1}\right), Y_{\mathcal{E}}\left(b(x), x_{2}\right)\right]=Y_{\mathcal{E}}\left([a, b](x), x_{2}\right) x_{1}^{-1} \delta\left(\frac{x_{2}}{x_{1}}\right) . \tag{3.10}
\end{equation*}
$$

This shows that $\left\langle U_{W}\right\rangle$ is an $L(\mathfrak{g})$-module with $a(z)=Y_{\mathcal{E}}(a(x), z)$ for $a \in \mathfrak{g}$. Furthermore,

$$
a(x)_{0} b(x)=[a, b](x), \quad a(x)_{n} b(x)=0 \quad \text { for } n \geq 1 .
$$

Then it follows from the construction of $V_{\mathfrak{g}}$ that there exists an $L(\mathfrak{g})$-module homomorphism $\psi_{W}$ from $V_{\mathfrak{g}}$ to $\left\langle U_{W}\right\rangle$, sending $a$ to $a(x)$ for $a \in \mathfrak{g}$.

Now, we specialize $W=V_{\mathfrak{g}}$ and we denote the corresponding $L(\mathfrak{g})$-module homomorphism $\psi_{W}$ by $\psi_{x}$. For $v \in V_{\mathfrak{g}}$, set

$$
Y(v, x)=\psi_{x}(v) \in\left\langle U_{V_{\mathbf{s}}}\right\rangle \subset \operatorname{Hom}(V, V((x))) .
$$

We have

$$
Y(a, x)=\psi_{x}(a)=a(x) \quad \text { for } a \in \mathfrak{g}
$$

and furthermore, for $v \in V_{\mathfrak{g}}$,

$$
\begin{aligned}
& Y\left(Y\left(a, x_{0}\right) v, x_{2}\right)=Y\left(a\left(x_{0}\right) v, x_{2}\right)=\psi_{x_{2}}\left(a\left(x_{0}\right) v\right) \\
= & Y_{\mathcal{E}}\left(a(x), x_{0}\right) \psi_{x_{2}}(v) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right) a\left(x_{1}\right) \psi_{x_{2}}(v)-x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right) \psi_{x_{2}}(v) a\left(x_{1}\right)\right) \\
= & \operatorname{Res}_{x_{1}}\left(x_{0}^{-1} \delta\left(\frac{x_{1}-x_{2}}{x_{0}}\right) Y\left(a, x_{1}\right) Y\left(v, x_{2}\right)-x_{0}^{-1} \delta\left(\frac{x_{2}-x_{1}}{-x_{0}}\right) Y\left(a, x_{2}\right) Y\left(u, x_{1}\right)\right) .
\end{aligned}
$$

Now the first assertion immediately follows from Theorem 3.1 where the uniqueness follows from the spanning property.

Next, we come back to a general restricted $L(\mathfrak{g})$-module $W$. Recall that $\psi_{W}$ is an $L(\mathfrak{g})$-module homomorphism from $V_{\mathfrak{g}}$ to $\left\langle U_{W}\right\rangle$ with $\psi_{W}(a)=a(x)$ for $a \in \mathfrak{g}$. It follows that $\psi_{W}$ is a homomorphism of vertex Leibniz algebras. As $W$ is a $\left\langle U_{W}\right\rangle$ module, $W$ becomes a $V_{\mathfrak{g}}$-module through $\psi_{W}$.
Remark 3.6. Let $\mathfrak{g}$ be a Lie algebra, which is a Leibniz algebra with $\mathfrak{g}_{\text {Lie }}=\mathfrak{g}$. It follows from the constructions of $V_{\mathfrak{g}}$ and $V_{\hat{\mathfrak{g}}}(0,0)$ (recall Example 2.17) and the P-B-W theorem that $V_{\mathfrak{g}}$ is isomorphic to the $L(\mathfrak{g})$-submodule of $V_{\hat{\mathfrak{g}}}(0,0)$, generated by $\mathfrak{g}$. As $Y(a, x)=a(x)$ for $a \in \mathfrak{g}$, it follows that $V_{\mathfrak{g}}$ is a closed subspace. Then $V_{\mathfrak{g}}$ is a vertex Leibniz subalgebra. Furthermore, for $a, b \in \mathfrak{g} \subset V_{\hat{\mathfrak{g}}}(0,0)$, we have

$$
[a, b](-2) \mathbf{1}=[a(-1), b(-1)] \mathbf{1}=a(-1) b-b(-1) a \in V_{\mathfrak{g}} .
$$

Recall that $\mathcal{D} u=u(-2) \mathbf{1}$ for $u \in \mathfrak{g}$. We see that if $[\mathfrak{g}, \mathfrak{g}]=\mathfrak{g}$, then $\mathcal{D} V_{\mathfrak{g}} \subset V_{\mathfrak{g}}$ and $V_{\mathfrak{g}}$ is a vertex algebra without vacuum.
Proposition 3.7. Let $\mathfrak{g}$ be a Leibniz algebra and let $V_{\mathfrak{g}}$ be the associated vertex Leibniz algebra. Then $V_{\mathfrak{g}}$ is a vertex Leibniz subalgebra of an ordinary vertex algebra if and only if $\mathfrak{g}$ is a Lie algebra.
Proof. If $\mathfrak{g}$ is a Lie algebra, from Remark 3.6 we see that $V_{\mathfrak{g}}$ is isomorphic to the vertex Leibniz subalgebra of vertex algebra $V_{\hat{\mathfrak{g}}}(0,0)$, generated by $\mathfrak{g}$.

Now, assume that there exists a vertex algebra $V$ containing $V_{\mathfrak{g}}$ as a vertex Leibniz subalgebra. For $a, b \in \mathfrak{g} \subset V_{\mathfrak{g}}$, with $Y(a, x)=a(x)$ we have

$$
\begin{equation*}
a_{0} b=[a, b] \quad \text { and } \quad a_{n} b=0 \quad \text { for } n \geq 1 . \tag{3.11}
\end{equation*}
$$

On the other hand, as $V_{\mathfrak{g}}$ is a vertex Leibniz subalgebra of vertex algebra $V$, we have

$$
Y(a, x) b=e^{x \mathcal{D}} Y(b,-x) a
$$

where $\mathcal{D}$ is the linear operator of $V$, defined by $\mathcal{D}(v)=v_{-2} \mathbf{1}$ for $v \in V$. Then

$$
[a, b]=a_{0} b=\sum_{i \geq 0}(-1)^{i+1} \frac{1}{i!} D^{i} b_{i} a=-b_{0} a=-[b, a] .
$$

Thus $\mathfrak{g}$ must be a Lie algebra. Therefore, if $\mathfrak{g}$ is an authentic Leibniz algebra (not a Lie algebra), $V_{\mathfrak{g}}$ is not a subalgebra of a vertex algebra.

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[^1]:    ${ }^{4}$ This term is referencing an older paper by Huang and Lepowsky, but in the current context, there is more than one type of objects which the reader might naively call by this name.

